

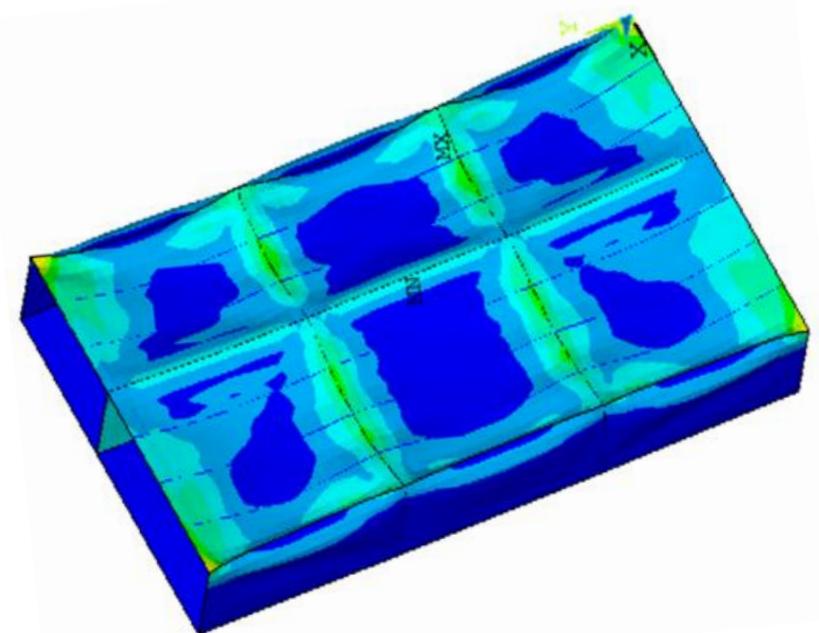


Rules and methods for dimensioning surface ship embarked materials subjected to underwater explosions.

Department of acoustics and vibrations STX France

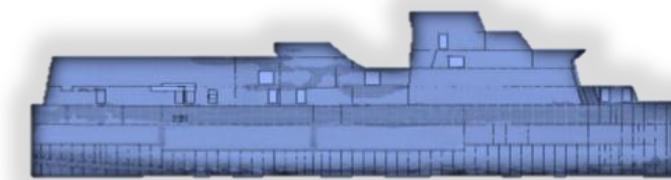
Mauricio García N

Supervisor: Pr. Hervé Le Sourne



Main parameters: *noncontact underwater explosion*

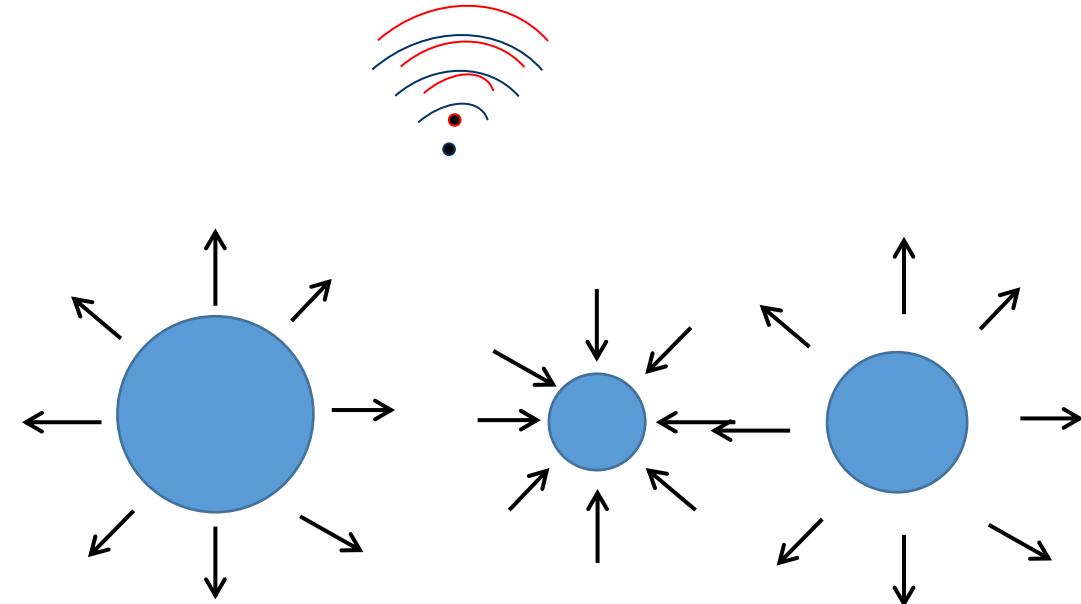
$$\text{Shock factor: } SF = \frac{\sqrt{W}}{D}$$



W : Weight of the charge

D : Stand off distance

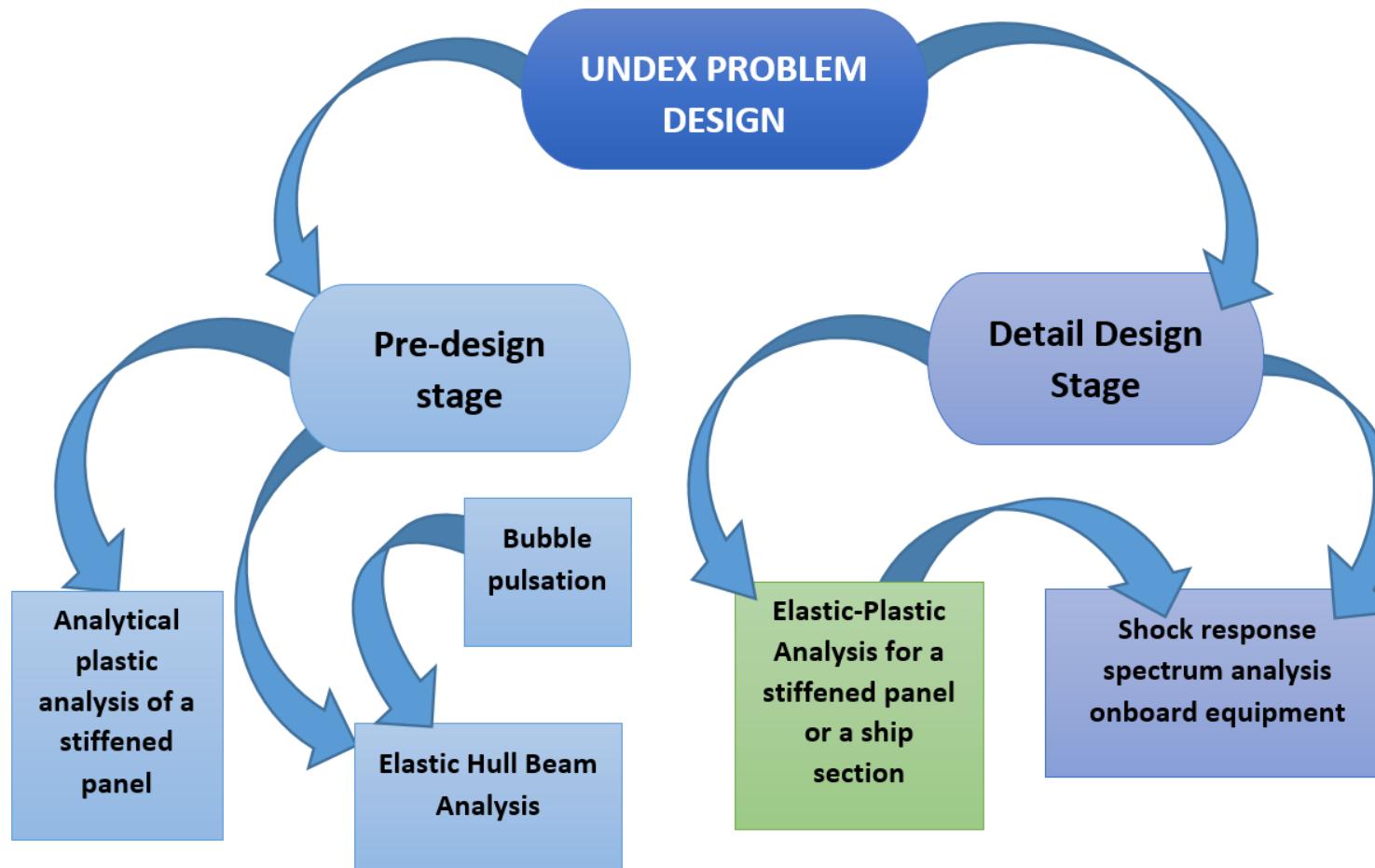
Bubble pulsation effect:



1. Objectives

1. - Key points identification for surface ships submitted to an UNDEX.
2. - Shock response rules for embarked materials.
3. - Simulation of a simplified structure submitted to an UNDEX.

2. Rules review

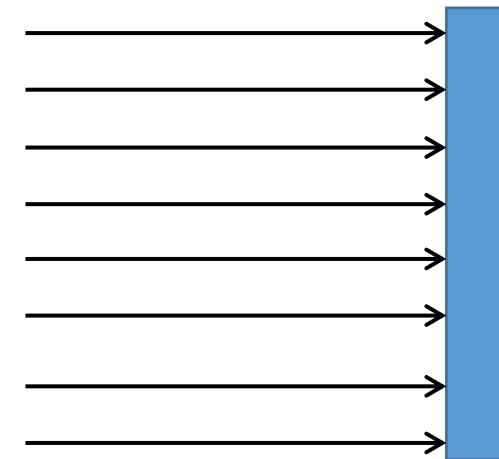


1. DDAM is the most referenced procedure for embarked materials.
2. BV/043 German rules.
3. French rules.

3. Taylor plate theory

$$\frac{P_i}{\rho c} = \frac{P_r}{\rho c} + v$$

Incident velocity Reflected velocity Plate velocity



Supposing

$$P_r = P_i - \rho c v$$

$$\text{Incident velocity } v_i = v_r \quad \text{Reflected velocity}$$

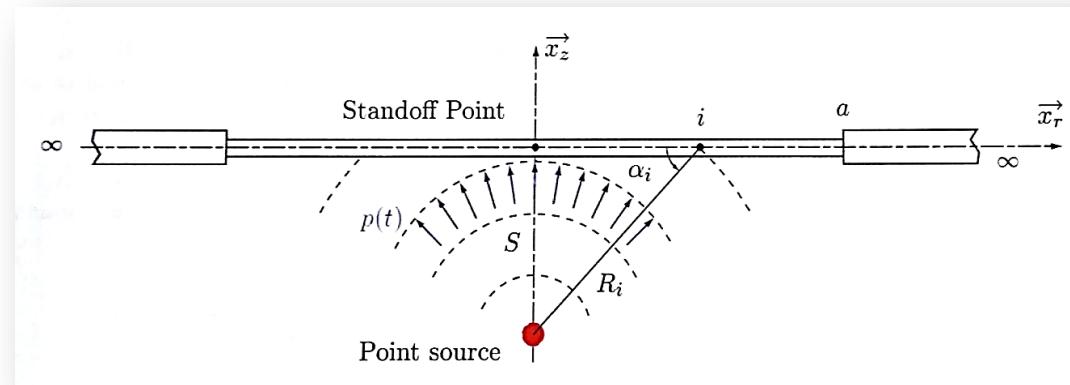
Considering that the surface is fixed

First term

$$P_t = 2P_i - \rho c v$$

$$v = \frac{2P_o}{\rho c Z - 1} \left(e^{-\frac{t}{Z\theta}} - e^{-\frac{t}{\theta}} \right)$$

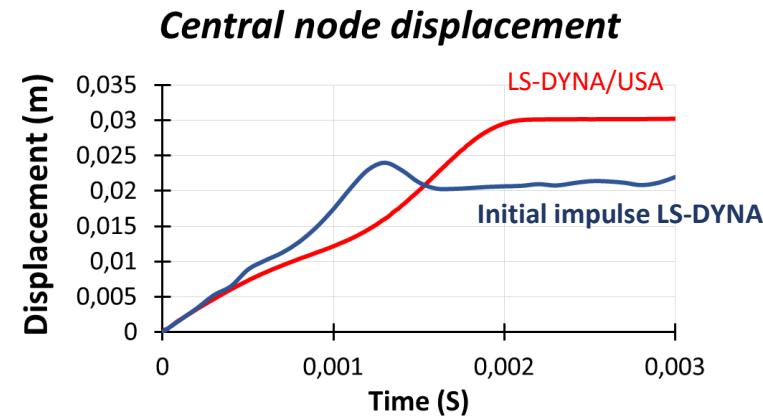
4. Impulse velocity approximation:



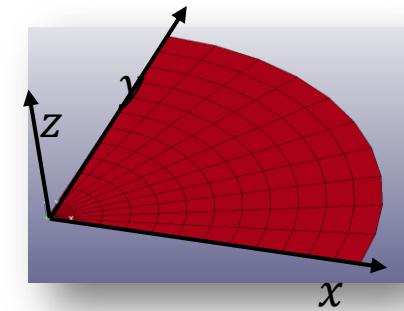
Pressure balance : $m \frac{dv_i}{dt} = 2p_{II}(t) - \frac{\rho c v_i(t)}{\sin \alpha_i}$

Impulse velocity: $v_{im} = \frac{2 \sin^2 \alpha_i p_m}{\rho c} \beta_i^{1/(1-\sin \alpha_i)}$

*Spherical wave approximation (SWA).
(Barras, 2007).*



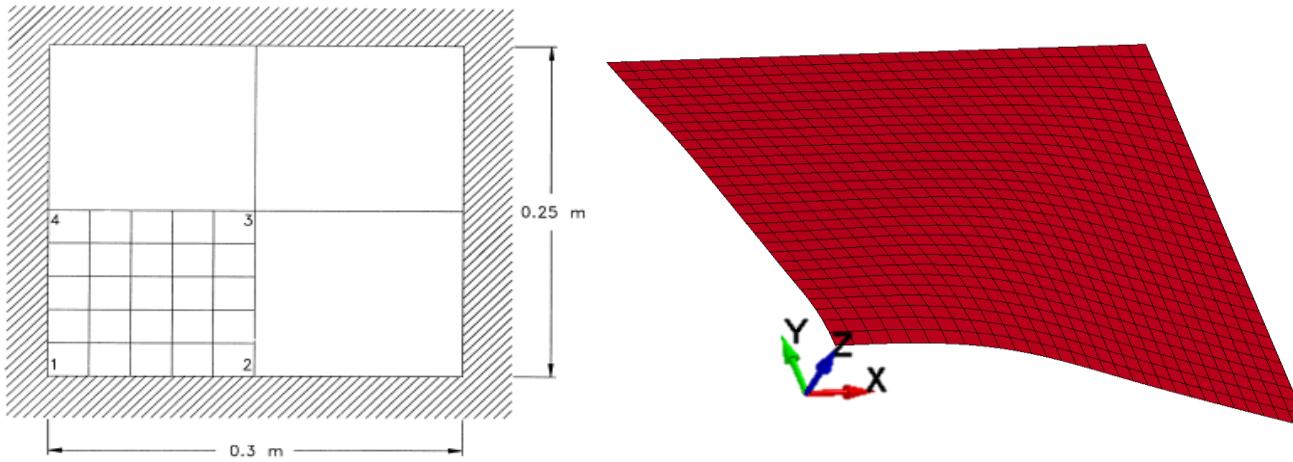
where: $2p_{II}(t) = 2p_0 \sin \alpha_i e^{-(t-t_0)/\theta}$



where: $\beta_i = \frac{\rho c \theta}{m \sin \alpha_i} = \frac{\beta}{\sin \alpha_i}$

4. Impulse velocity approximation: Simple plate analysis

Finite element model



(Ramajeyathilagam, K.; Vendhan, C.P.; Bhujanga Rao, V., 2000)

Boundary conditions

Along the y axis: $u_x = 0 \quad r_z = r_y = 0$

Along the x axis: $u_y = 0 \quad r_z = r_x = 0$

Full clamped conditions at the border

Materials:

- High strength steel
- Mild steel

→ **Objective: verify initial speed approach**

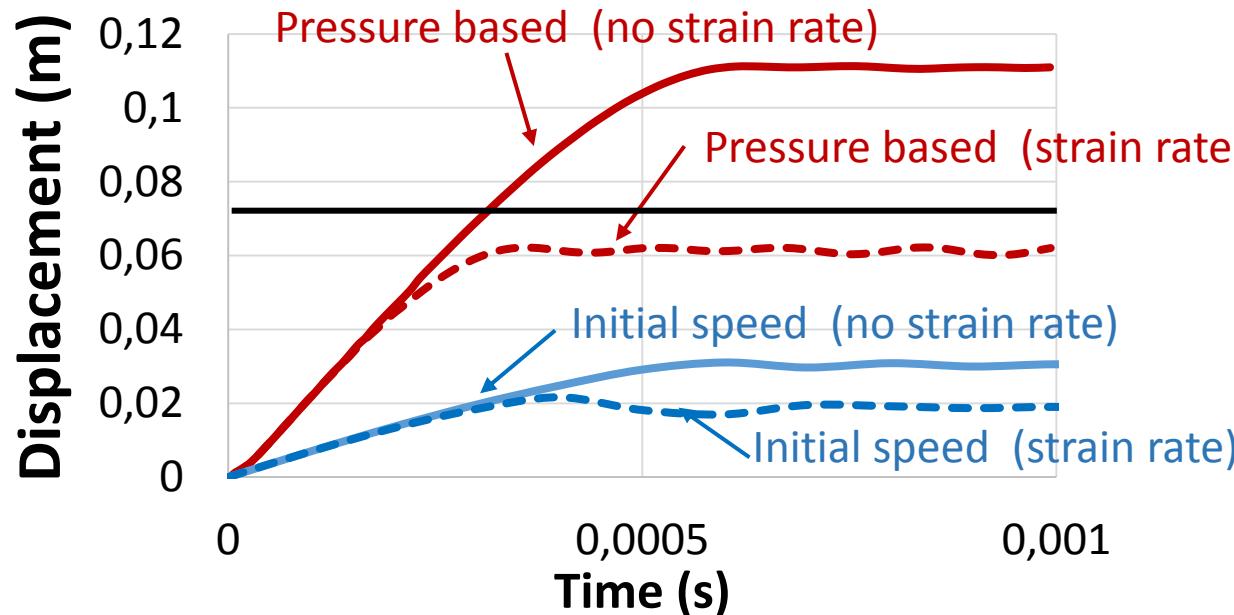
4. Impulse velocity approximation: Strain rate effect

Cowper Symonds material model:

$$\frac{\sigma_{dyn}}{\sigma_{stat}} = 1 + \left(\frac{\dot{\epsilon}}{D} \right)^{\frac{1}{p}}$$

Strain rate must be considered

Initial speed results

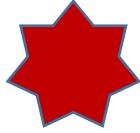


Data

Experimental Displacement (m)	Pressure based Displacement (m)	Shock factor
0,072	0,062	0,794

→ The initial velocity approximation underestimates the results.

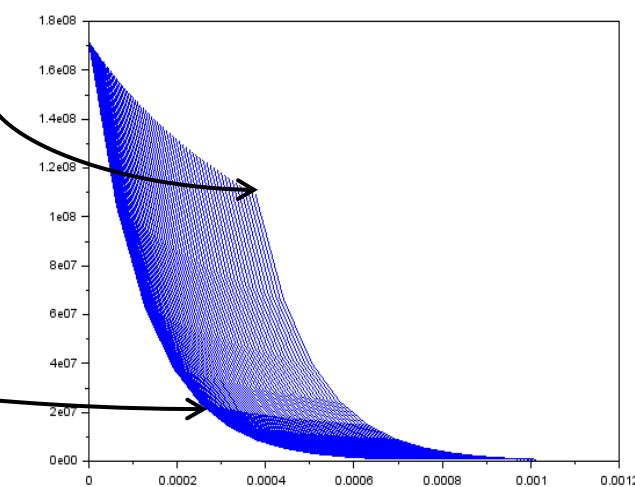
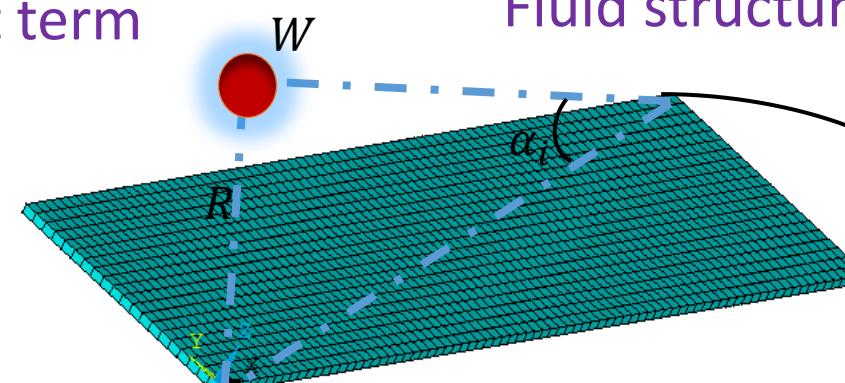
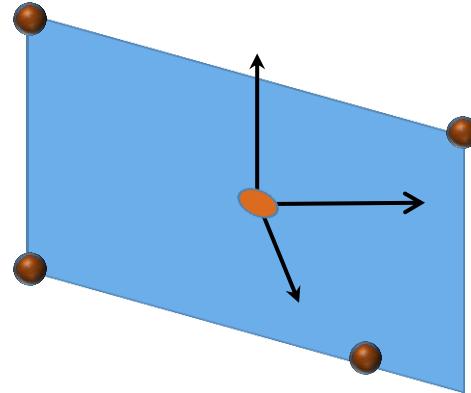
5. Pressure based approximation: Time history pressure for a single shell element.



$$P_{element} = 2P_0 \sin \alpha_i e^{-(t)/\theta} - \frac{\rho c}{m} \frac{2 \sin \alpha_i P_0}{(1 - \beta_i)} \frac{\theta}{\sin \alpha_i} \frac{(e^{-\beta_i t/\theta} - e^{-t/\theta})}{(e^{-\beta_i t/\theta} - e^{-t/\theta})}$$

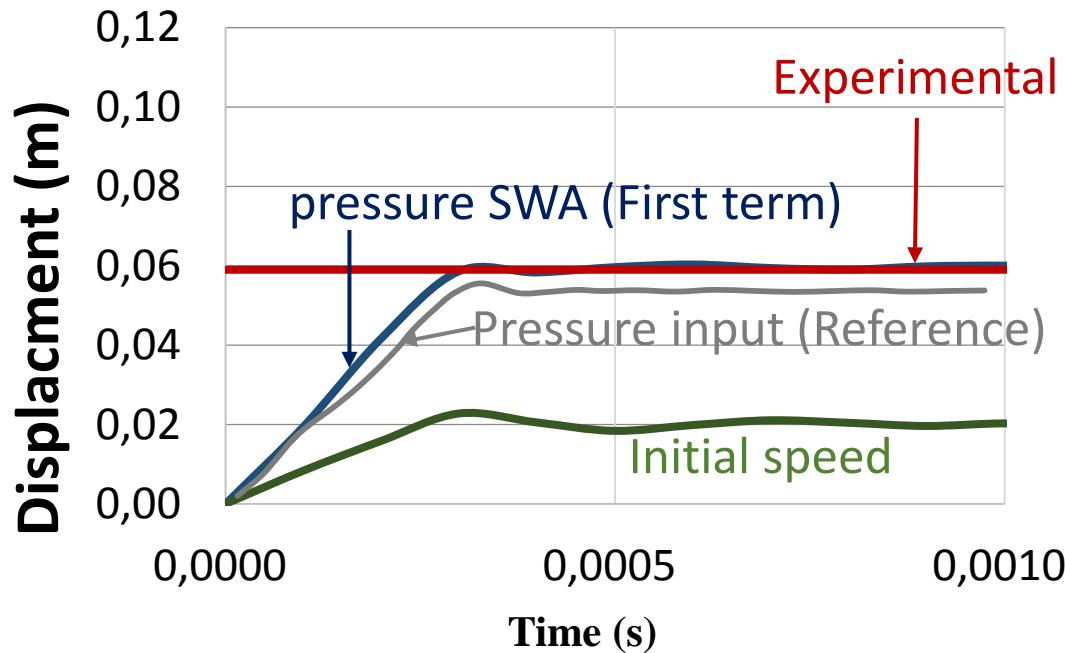
First term

Fluid structure interaction

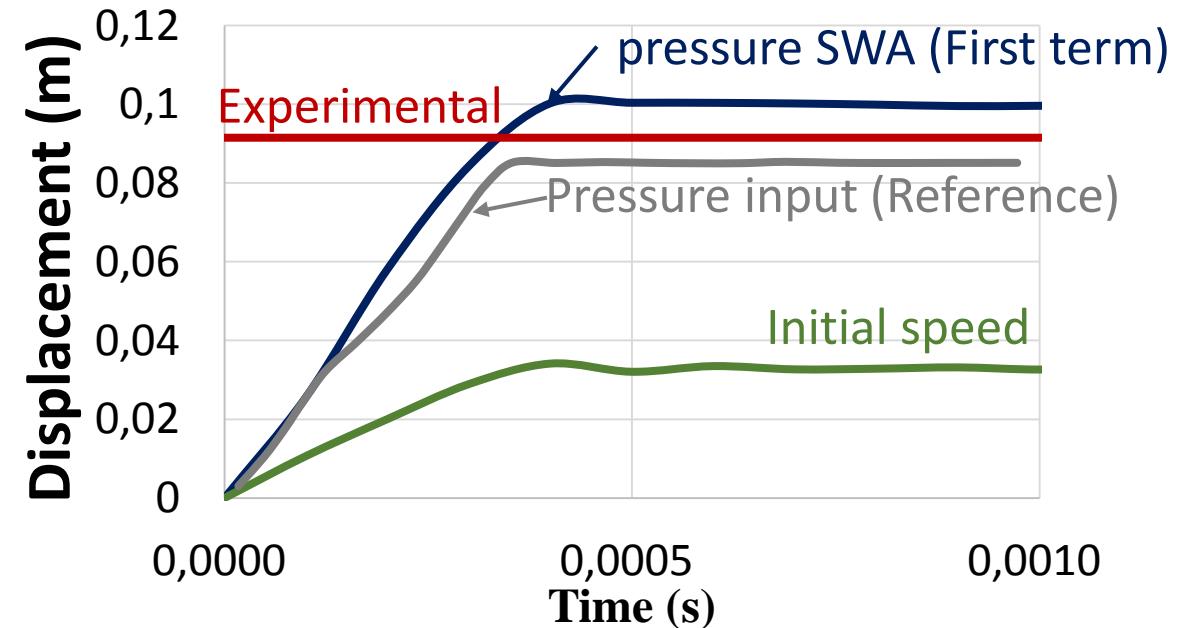


5. Pressure based approximation: Pressure input first term

Shock Factor 0,794 High strength steel

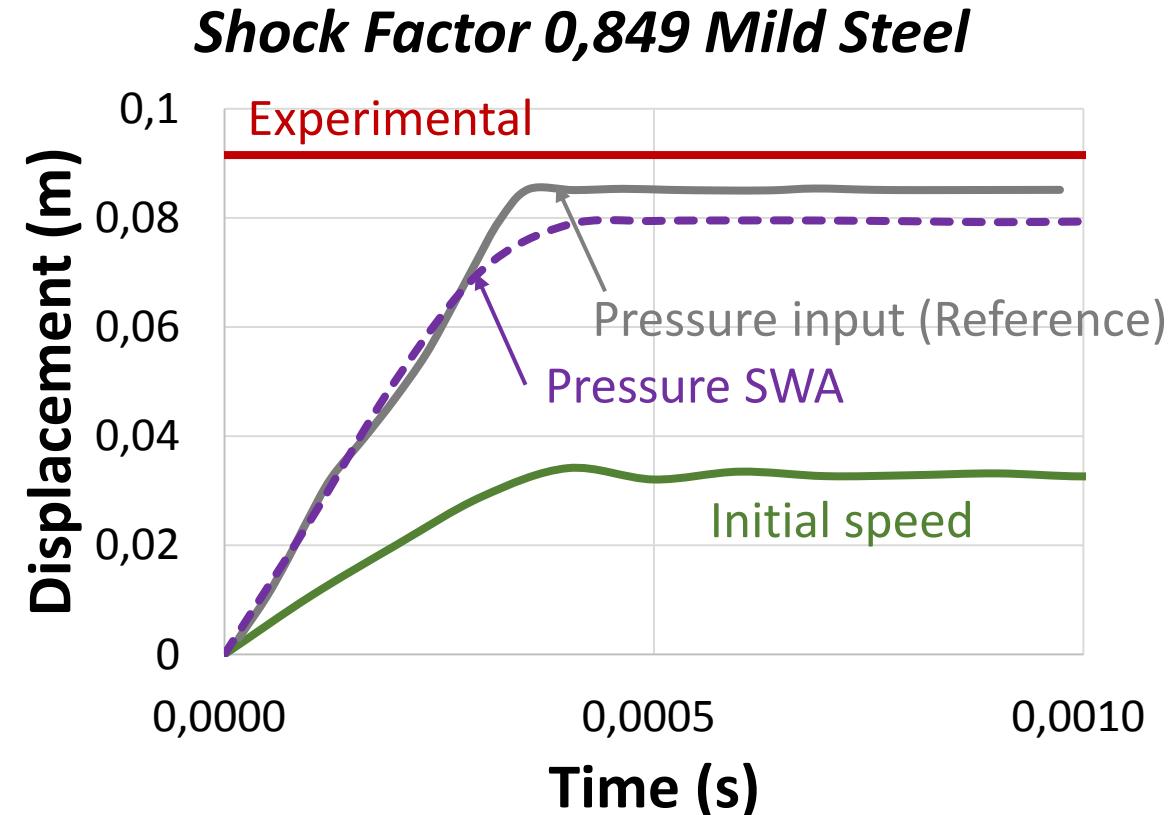
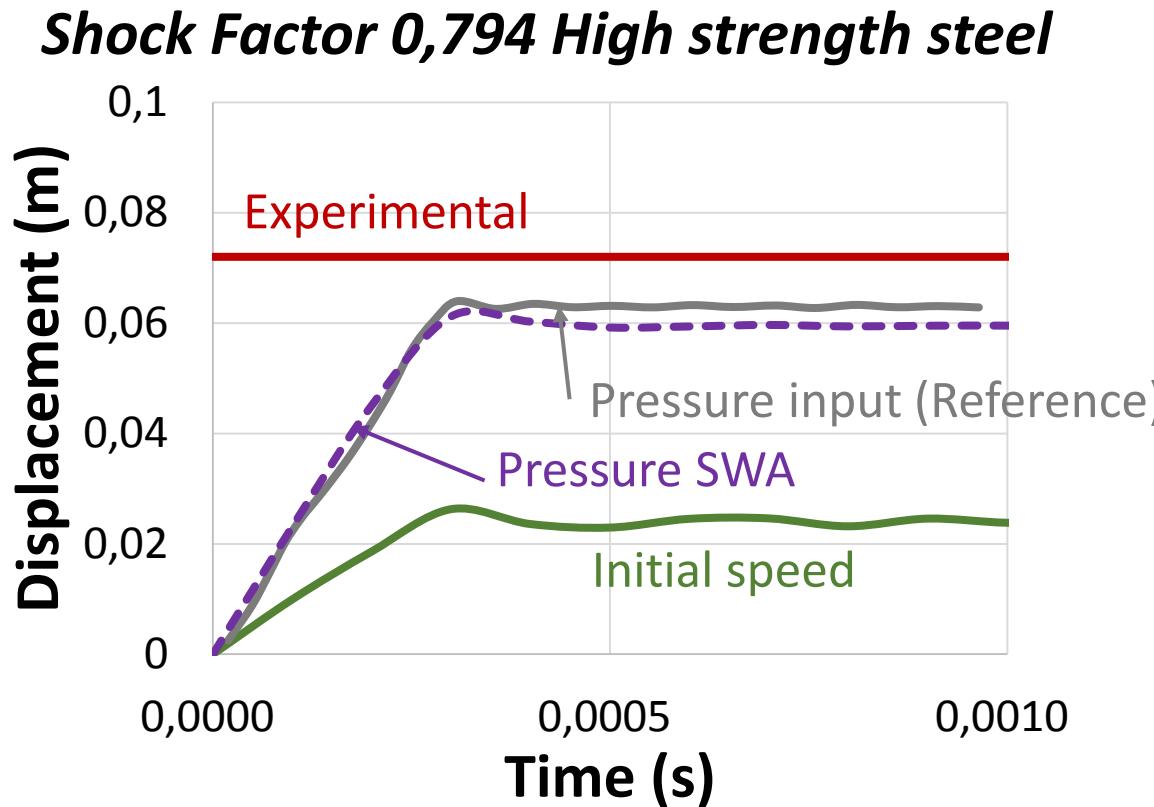


Shock Factor 0,849 Mild Steel



➡ **Final deformation (slightly) found above the experimental results.**

5. Pressure based approximation: SWA full equation.



Results similar to the reference.

5. Pressure based approximation: ANSYS & LS-DYNA material model.

- ANSYS does not have explicit solution option (LS-DYNA only)

Full transient simulation.

Implicit solution



Perzyna model

$$\dot{\varepsilon}_{pl} = \gamma \left(\frac{\sigma}{\sigma_0} - 1 \right)^{1/m}$$

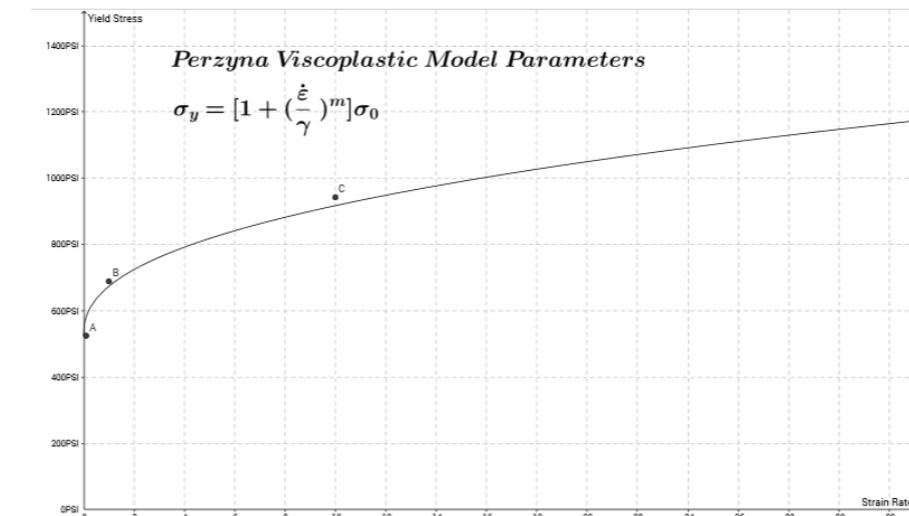
Explicit solution



Cowper Symonds

$$\frac{\sigma_{dyn}}{\sigma_{stat}} = 1 + \left(\frac{\dot{\varepsilon}}{D} \right)^{\frac{1}{p}}$$

Yield stress



Strain rate

Taken from: <https://www.geogebra.org/m/26707>

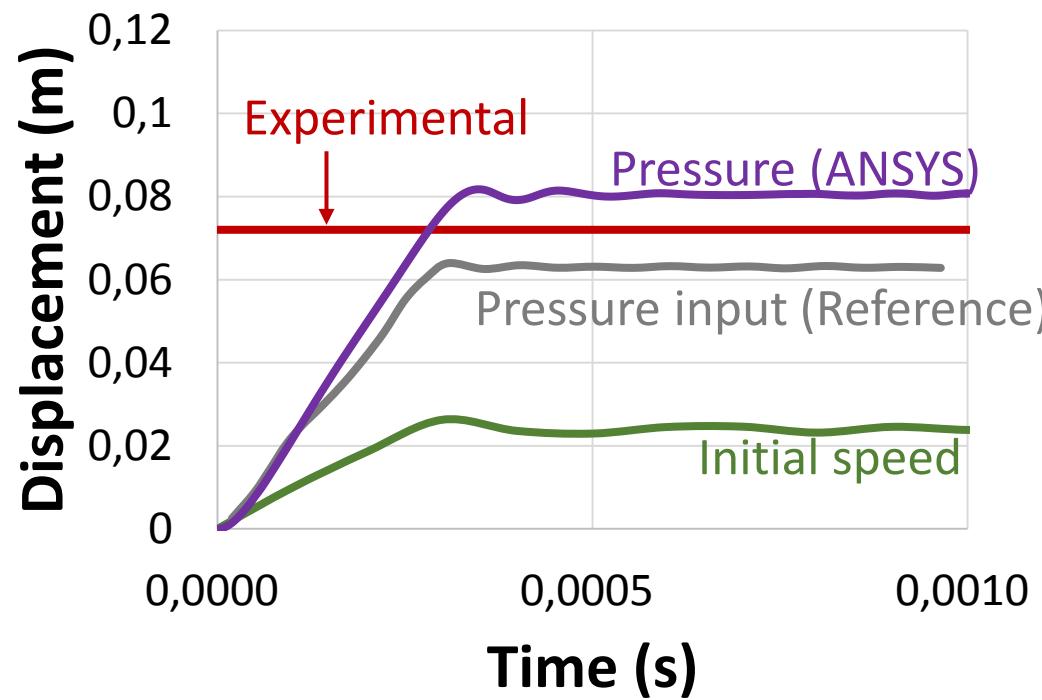
$$1/p = m \text{ and } \gamma = D$$

D = 40 & m = 5 for steel.

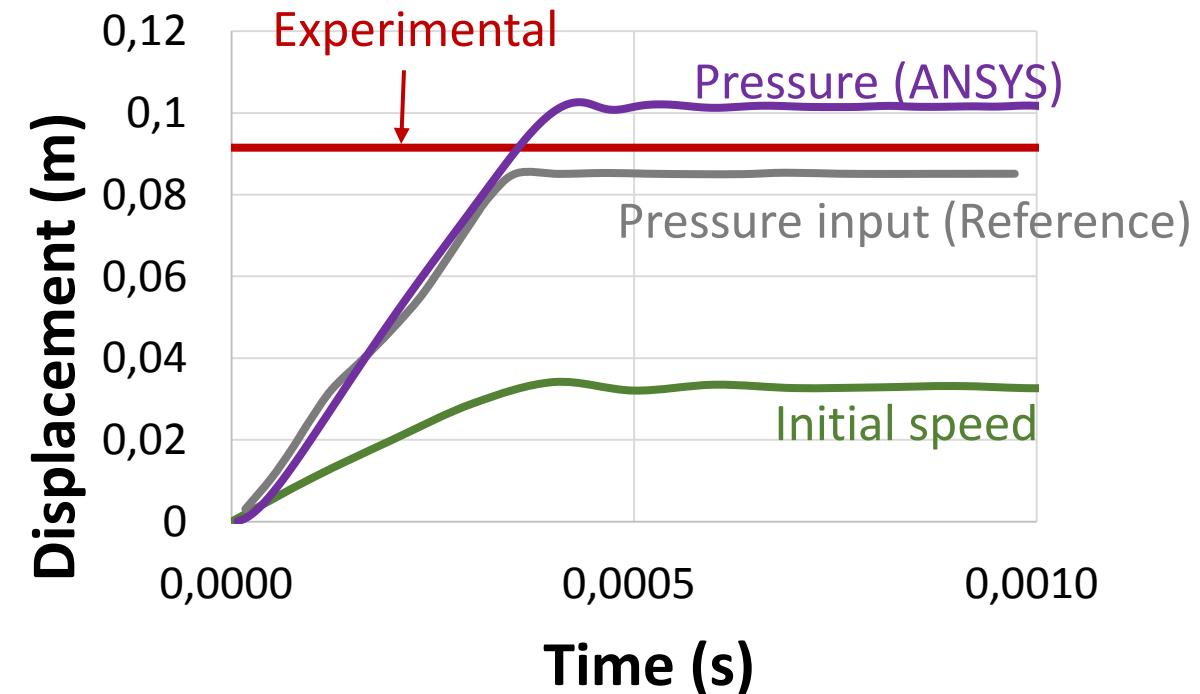
→ *Same equation.*

5. Pressure based approximation: Results validation using ANSYS.

Shock Factor 0,794 High strength steel



Shock Factor 0,849 Mild steel



→ **Results above the ones obtained using LS-DYNA.**

5. Pressure based approximation: Results summary

4 loading approaches tested

- Initial impulse**
Largely underestimates the damage
- Initial impulse + added mass**
Underestimates the damage
- Pressure only**
Slightly overestimates but conservative!
- Pressure + FSI**
Oscillates near experimental results.

Hard Strength Steel	Shock Factor (SF)	Experimental (m)	SWA Pressure based input (m)	%Error	Initial impulse formulation (m)	%Error	Pressure based input Two Terms (m)	%Error	Added mass Approach (m)	%Error
	0,424	0,032	0,034	7,19	0,0156	-51,25	0,0349	9,06	0,026	-20,31
Mild Steel	0,671	0,059	0,060	2,20	0,0228	-61,36	0,0525	-11,02	0,038	-35,76
	0,794	0,072	0,074	2,78	0,0263	-63,47	0,0612	-15,00	0,044	-39,17
Mild Steel	Shock Factor (SF)	Experimental (m)	SWA Pressure based input (m)	%Error	Initial speed formulation (m)	%Error	Pressure based input Two Terms (m)	%Error	Added mass Approach (m)	%Error
	0,671	0,0675	0,077	14,37	0,0277	-58,96	0,0643	-4,74	0,046	-31,70
	0,794	0,0759	0,093	22,79	0,0322	-57,58	0,0748	-1,45	0,054	-29,51
	0,849	0,0915	0,100	9,29	0,0341	-62,73	0,0795	-13,11	0,057	-38,14

*4 Different loading approaches
60 calculations using LS-DYNA or ANSYS*

6. Stiffened plate : ANSYS compared to LS-DYNA

Material Properties

	Quench Steel	Mild steel
Young Modulus (MPa)	400	250
Tangent Modulus (MPa)	631	350
Poisson ratio	0,3	0,3

Boundary Conditions

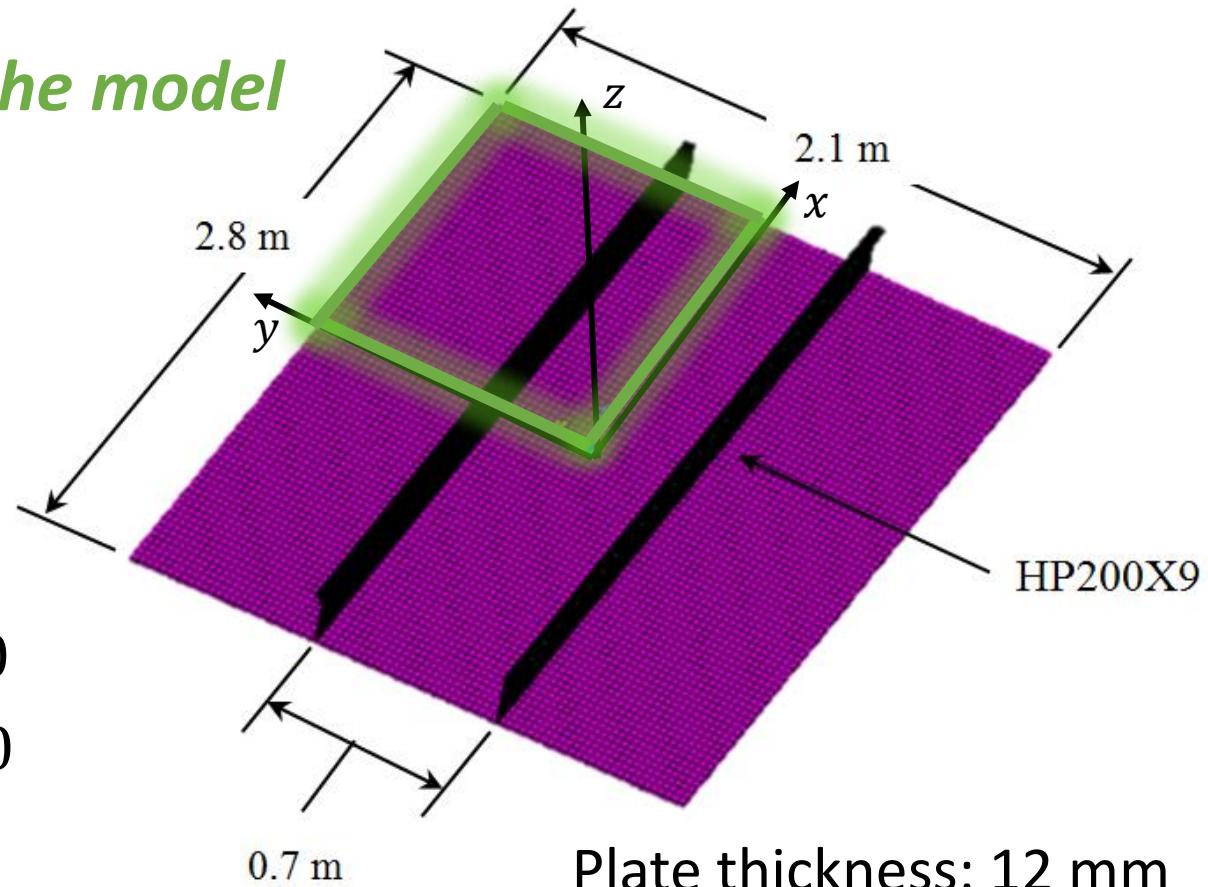
Along the y axis: $u_x = 0$ $r_z = r_y = 0$

Along the x axis: $u_y = 0$ $r_z = r_x = 0$

Full clamped conditions at the border

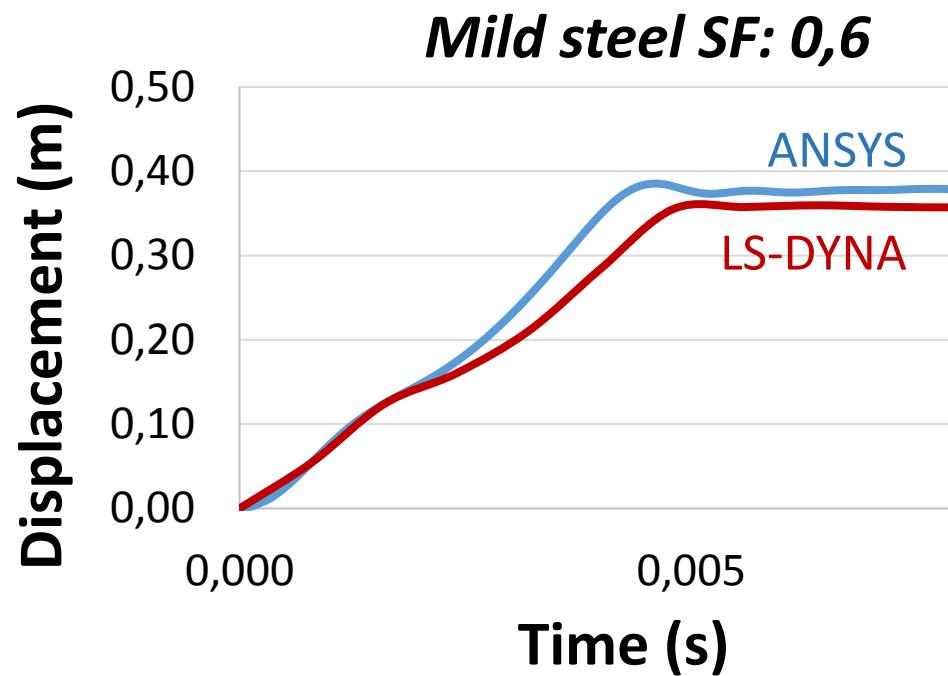
Finite element model

% of the model



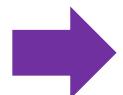
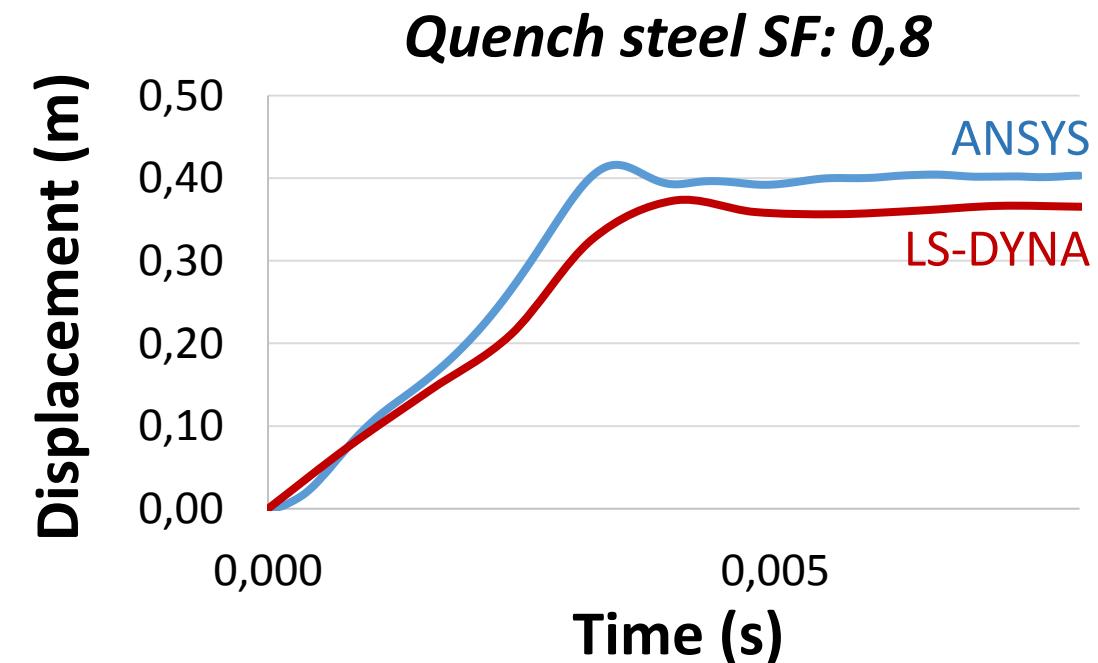
6. Stiffened plate : ANSYS compared to LS-DYNA

Shock factor increased until rupture



Erosive law.

$$Ef = 0.056 + 0.54 \frac{t}{l_e}$$



Results obtained by the two software are similar.

6. Stiffened plate : ANSYS compared to LS-DYNA

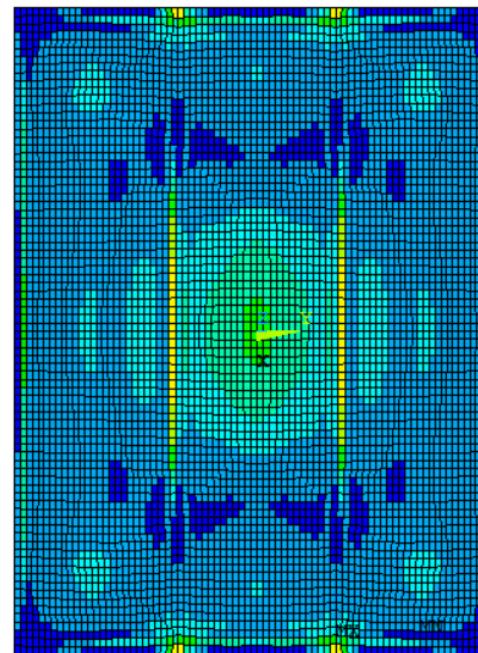
Mild Steel

SF	LS-DYNA	ANSYS	ERROR %
0,44	0,25	0,25	2,89
0,55	0,33	0,34	5,35
0,6	0,36	0,38	6,16

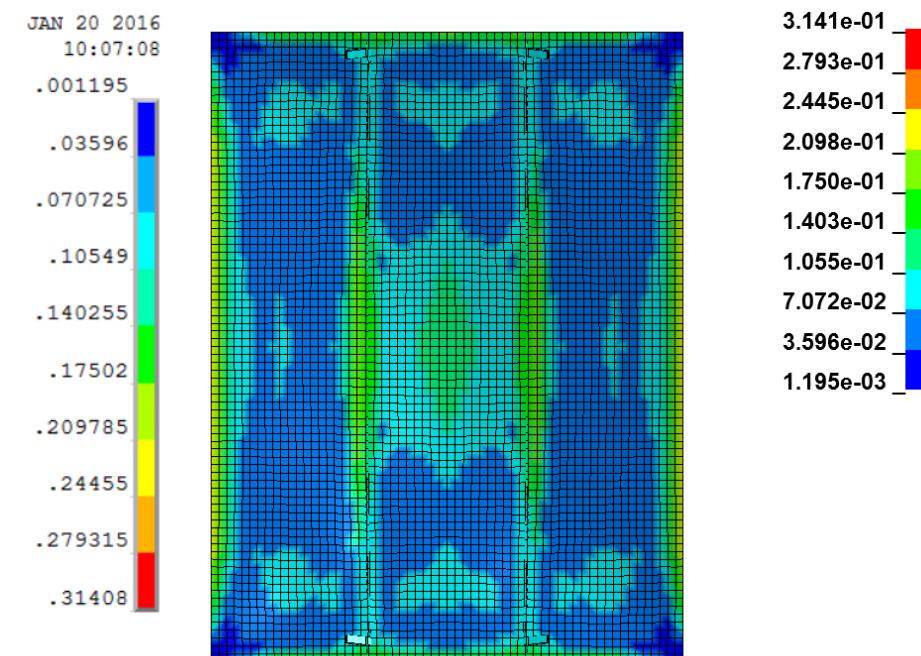
Quench Steel

SF	LS-DYNA	ANSYS	ERROR %
0,66	2,94	3,04	3,40
0,77	0,35	0,36	4,82
0,833	0,36	0,40	9,86

ANSYS results



LS-DYNA results



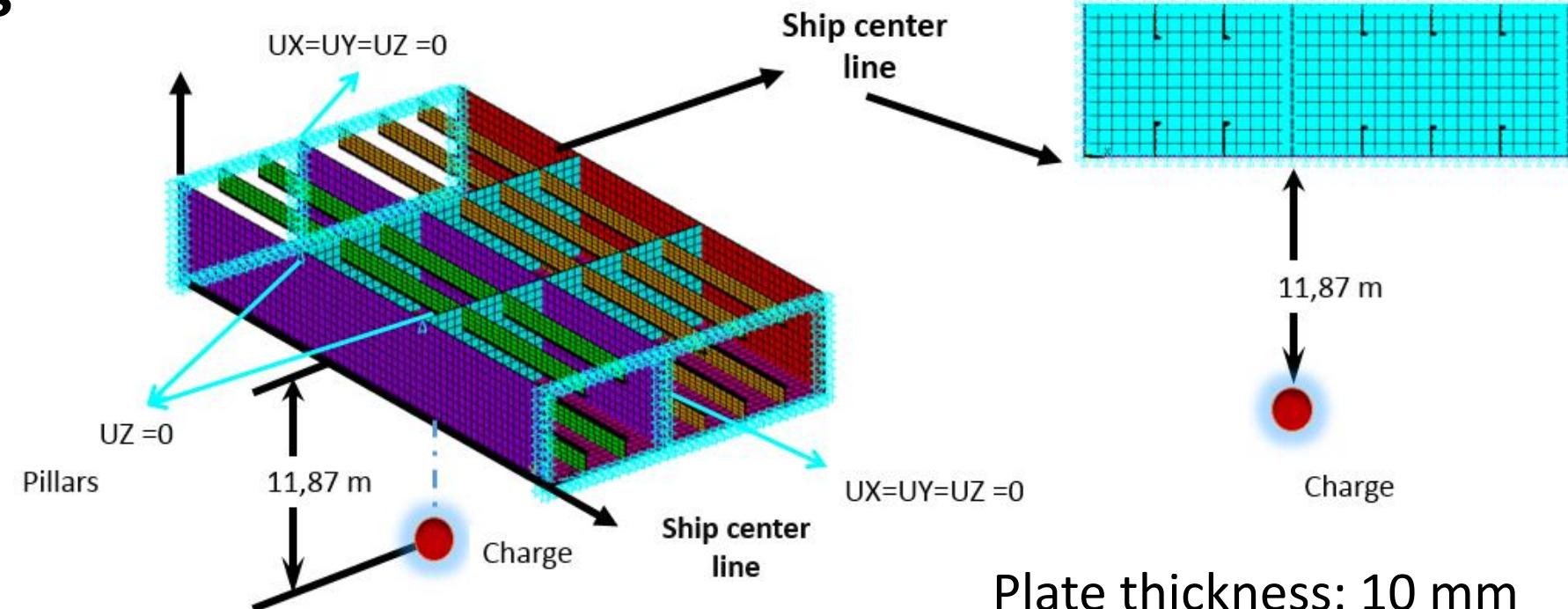
→ *Similar pattern on the distributions of plastic strains*

7. Ship full section: ANSYS compared to LS-DYNA.

Same procedure applied to the stiffened plate.

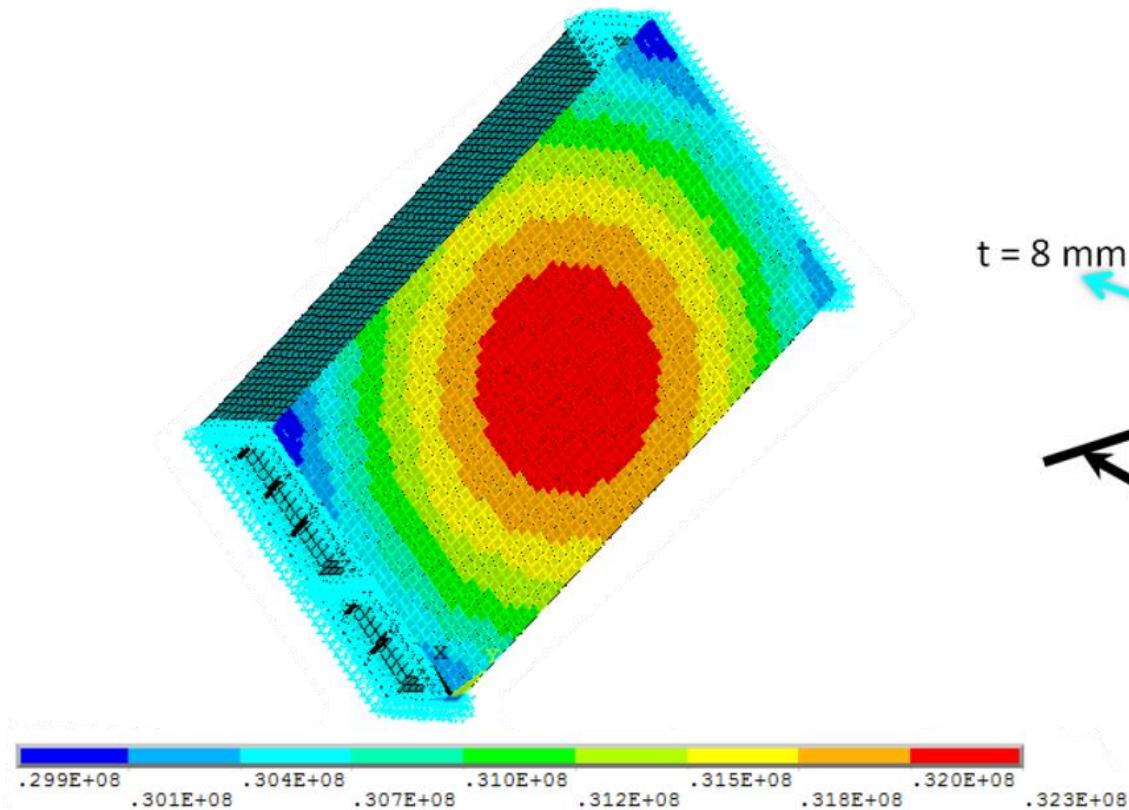
Boundary Conditions

Restricted displacement at the edges. Rotation is allowed.

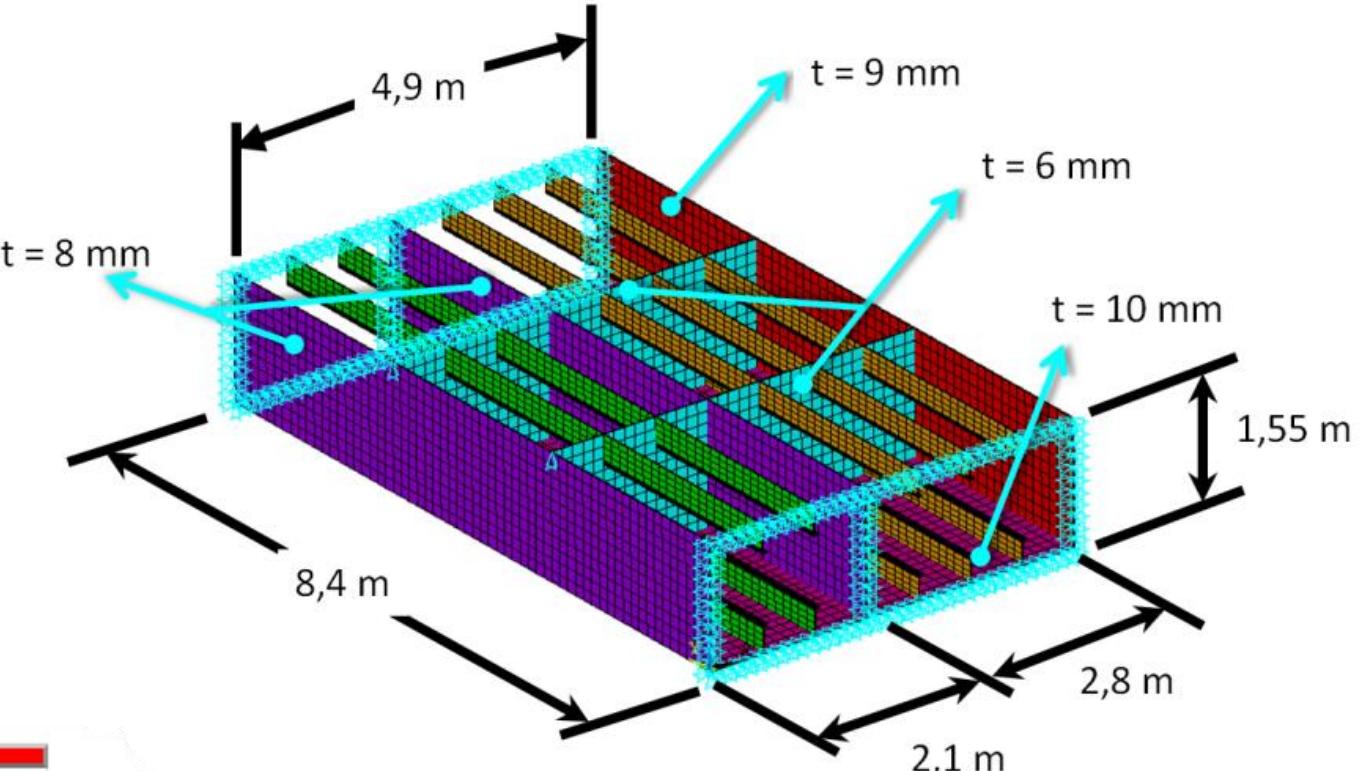


7. Ship full section: ANSYS compared to LS-DYNA.

First load step

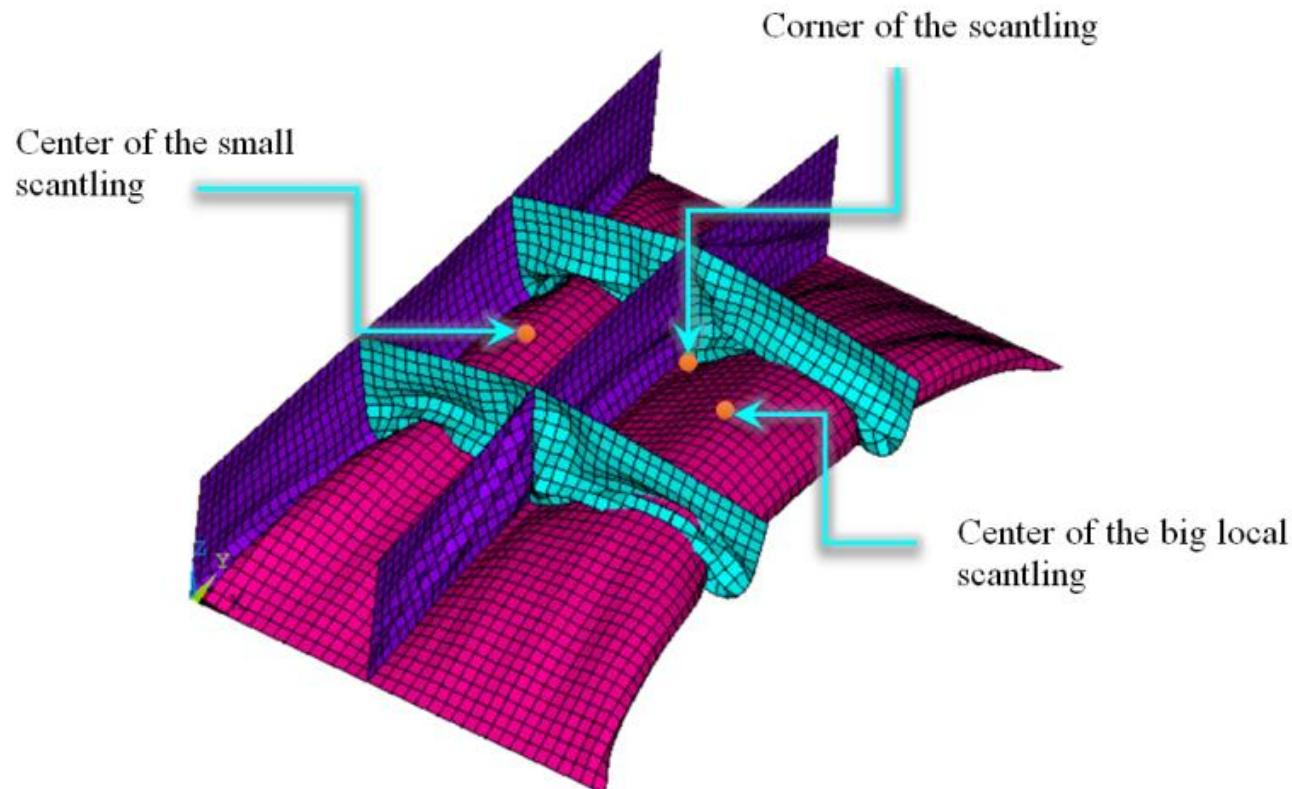


Scantling dimensions



7. Ship full section: ANSYS compared to LS-DYNA.

Points being measured



7. Ship full section: ANSYS compared to LS-DYNA.

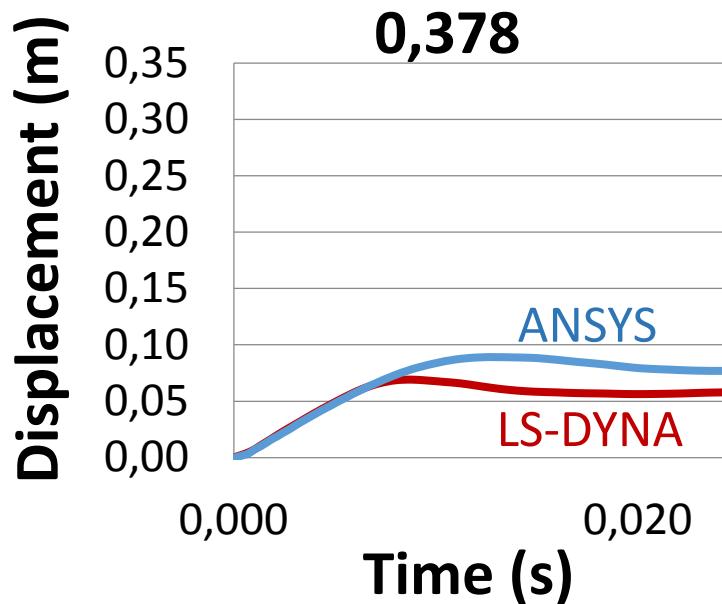
Exact modeling: number of elements – stiffeners – load profile.

Maximum:

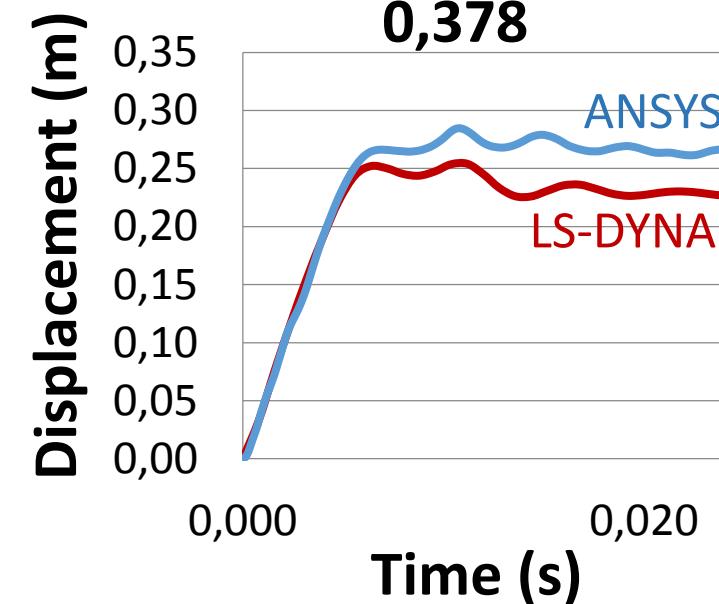
Mild Steel SF: 0,378.

Quench Steel SF: 0,489

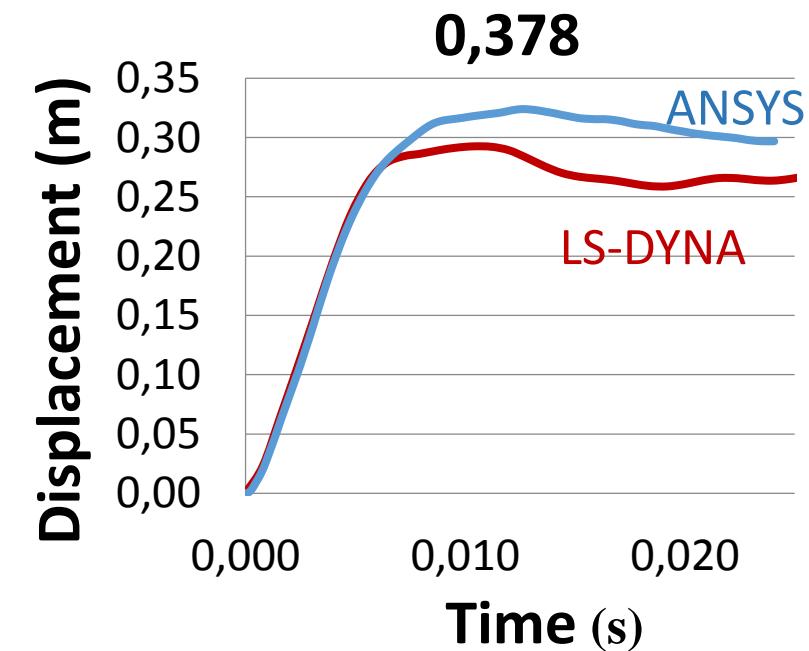
MS-Corner scantling SF-



MS-Small scantling SF-



MS-Large scantling SF-

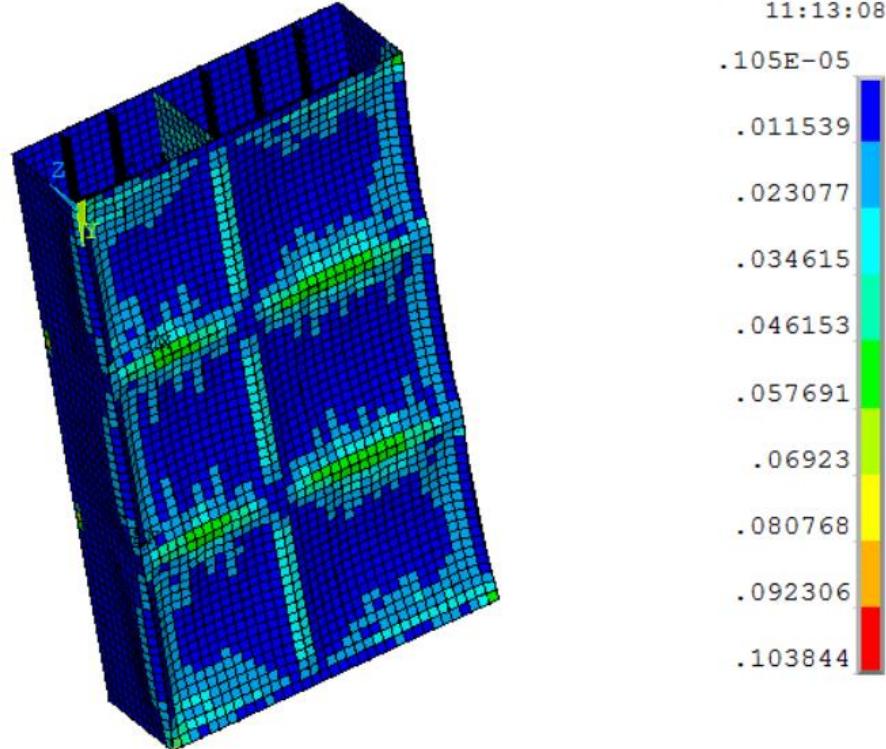


Slightly overshoot possibly due to the element formulation.

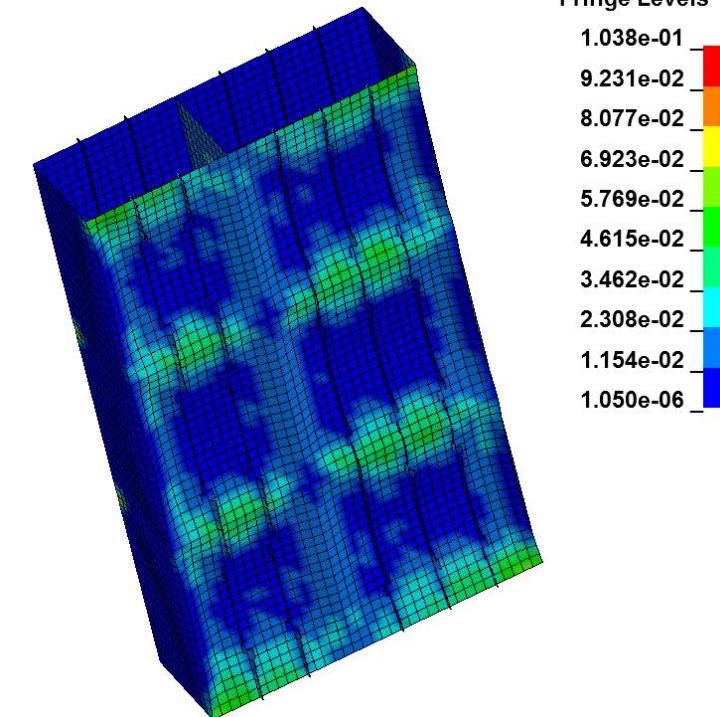
7. Ship full section: ANSYS compared to LS-DYNA.

Plastic strain comparison using Mild Steel S.F.:0,33.

ANSYS results



LS-DYNA results



→ *Plastic strain distribution present the same pattern.*

8. Conclusions

- The initial speed approach underestimates the experimental results.
- The results obtained by the pressure, neglecting the second term, overestimate the level of deformation.
- LS-DYNA and ANSYS end up having approximately similar results. Considering the rupture strain of the plate.
- Discrepancies occur between LS-DYNA and ANSYS. Those discrepancies are probably due to the solvers themselves and to the formulation of the shell elements used.

MANY THANKS:

Special thanks to:

- Supervisor: Hervé Le Sourne.
- Reviewer: Phillippe Rigo.
- Reviewer: Lionel Gentaz.
- Sylvain Branchereau.
- Marc Yu.
- Clement Lucas.

But also to:

- Department of Acoustics and Vibrations @ STXFrance.
- All of the professors and students @ ICAM.



Lloyd's Register
Foundation

